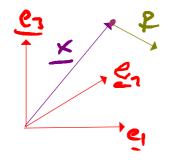
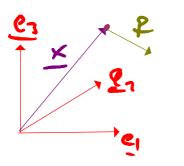
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$$H = \frac{\underline{p} \cdot \underline{p}}{2M} + V(\underline{x}). \tag{7.1}$$

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$$\int |\psi(\underline{x},t)|^2 d^3x = 1.$$
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V. (x) = 4:(x) e -: E: Th stationing state Then $|T_{1}(x)|^{2} = |2-(x)|^{2} + -inleq$. $\widetilde{\mathcal{Z}}_{\mathcal{C}}:\widetilde{\Psi}_{\mathcal{C}}(\mathscr{C}) = \widetilde{\mathcal{Z}}_{\mathcal{C}}:\mathcal{U}_{\mathcal{C}}(\mathscr{C}) = \widetilde{\mathcal{L}}_{\mathcal{L}}$ But. does not have stationary [4:(=)]?. (f. 1).

Real in ID we used an ansatz 4(x,t) = 4(x).T(t) and then argued the general subtrantis a Superpresidion of these product state solutions. In 30 we try 2 (x, +) = 24(x) T(H) $= \int f(4)(x) = E \cdot 4(x) \quad (just as)$ $T(t) = e^{-iEt} f_{th} \quad (just as) \quad (in \ TD)$ Our theorems from 1D carry over: the general solution to the 3DSE is again a superposition of stationary state solutions (for discrete energy) spectrum $\frac{1}{2} \frac{1}{2} \frac{1}$

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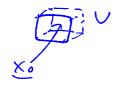
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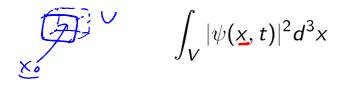
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 $-\frac{\hbar^2}{2M}\nabla^2\psi(\underline{x},t) + V(\underline{x})\psi(\underline{x},t) = i\hbar\frac{\partial}{\partial t}\psi(\underline{x},t).$ (7.7) $\nabla \overline{J} = -\frac{i}{2m} \left(\left(\overline{V} + \frac{1}{2m} +$ $-(v^{2}u^{2})v_{-}(v^{2}u^{2})v_{+}(v^{2})$ $= \frac{1}{2n} \left(\frac{1}{4} \left(\frac{1}{2} + 1 \right) - \left(\frac{1}{2n} + 1 \right) \right)$ $\frac{-it}{2} \mathcal{U}^{\dagger} \left(\frac{2\pi i t}{t^2} \frac{3\mu}{r} + \frac{2\pi}{t^2} \mathcal{U}^{\dagger} \mathcal{U}^{\dagger} \mathcal{U}^{\dagger} \right)$ $+\frac{it}{im}\left(\left(\frac{2mit}{42}\right)\frac{24^{\circ}}{2+}\right)\frac{4}{2}+\frac{2m}{42}\sqrt{22^{\circ}}\frac{24^{\circ}}{2+}\right)$ $= -2t^{*}\frac{\partial 2t}{\partial t} - 2t\frac{\partial 2t^{*}}{\partial t} = -\frac{\partial}{\partial t}(2t^{*}2t) = -\frac{\partial p}{\partial t}.$

Notice that the 3D Schrödinger equation, like the 1D SE, is linear and the superposition principle thus applies to its solutions:

The Born rule naturally extends to the 3D case:





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Notice that the 3D Schrödinger equation, like the 1D SE, is linear and the superposition principle thus applies to its solutions: there is a physical solution corresponding to any linear combination of two (or more) physical solutions.

$$\int_{V} |\psi(\mathbf{x},t)|^2 d^3x \approx V |\psi(\underline{x}_0,t)|^2$$
(7.12)

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$$= V \rho(\underline{x}_{0}, t).$$
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$$\langle \hat{A} \rangle_{\psi} = \int \psi^*(\underline{x}, t) A \psi(\underline{x}, t) d^3 x = (\psi, A \psi).$$
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As in the 1D case, we can justify this definition directly for position and for operators with discrete eigenvalues. It can also be justified for general operators: we will take the definition (7.13) as valid for all operators.

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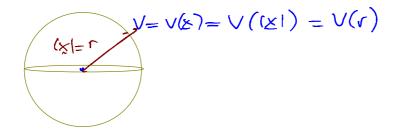
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We can thus define the uncertainty $\Delta_{\psi}A$ as in (6.21), using the definition (7.13) for expectation values.

$$(\Delta_{\psi} A)^2 = \langle (A - \langle A \rangle_{\psi})^2 \rangle_{\psi}$$

= $\langle A^2 \rangle_{\psi} - (\langle A \rangle_{\psi})^2 .$ (6.21)

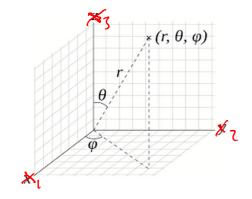
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It is convenient to use spherical polar coordinates

$$x_1 = r \sin \theta \cos \phi$$
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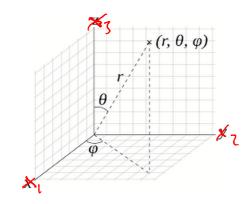


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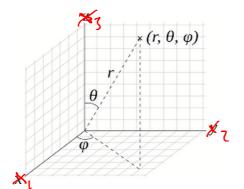


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$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \quad (7.15)$$

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$$= \frac{1}{r}\frac{d^{2}}{dr^{2}}(r\psi). \qquad (7.16)$$

Hence

$$-\frac{\hbar^2}{2M} \frac{1}{r} \frac{d^2}{dr^2} (r\psi(r)) + V(r)\psi(r) = E\psi(r), \qquad (7.17)$$

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$$-\frac{\hbar^2}{2M}\frac{1}{r}\frac{d^2}{dr^2}(r\psi(r)) + V(r)\psi(r) = E\psi(r), \qquad (7.17)$$

which we can rewrite as

$$-\frac{\hbar^2}{2M}\frac{d^2}{dr^2}(r\psi(r)) + V(r)(r\psi(r)) = E(r\psi(r)). \quad (7.18)$$

Notice that (7.18) is the 1D time-independent SE for $\phi(r) = r\psi(r)$, on the interval $0 \le r < \infty$.

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Conversely, any odd parity solution of the 1D SE for $-\infty < r < \infty$ defines a solution to (7.18) with $\phi(r) \rightarrow 0$ as $r \rightarrow 0$ and $\frac{d\phi}{dr}$ finite at r = 0. Provided that V(r) is finite and continuous at r = 0, these continuity conditions imply that ψ and ψ' are continuous at the origin.

$$-\frac{\hbar^2}{2M}\frac{d^2}{dr^2}(r\psi(r)) + V(r)(r\psi(r)) = E(r\psi(r)).$$
(7.18)

 $\frac{-5}{10}p'(1) + \sqrt{1}p(1) = Ep(1)$ $\implies \lim_{s \to \infty} (p''(s)) = 0 \quad \text{(if } V \text{ non-singular})$ b'(s) = 24(1s) + 54''(s) $\implies \lim_{r \to 0^+} (r_{+}'(v)) = \lim_{r \to 0^+} (p''(r) - r^2 + r'_{0})$ Ο.

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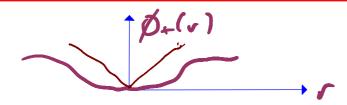
Solving (7.18) thus becomes equivalent to finding odd parity solutions to the 1D SE for $-\infty < r < \infty$.

We will show later (see Thm. 15) that the ground state (the lowest energy bound state, if there is one) of a 3D quantum system with spherically symmetric potential is itself spherically symmetric.

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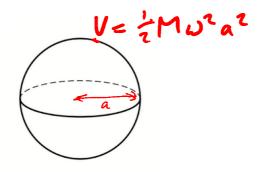
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Examples of spherically symmetric potentials

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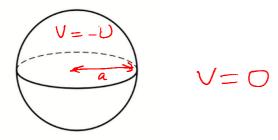
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spherically symmetric

1D harmonic oscillator bound states The spherical square well has potential

$$V(r) = \begin{cases} -U & r < a, \\ 0 & r > a. \end{cases}$$
(7.21)

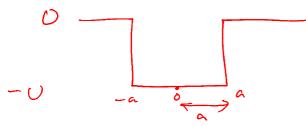


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By the above argument, spherically symmetric stationary states correspond to odd parity bound states of the 1D square well potential

$$V(x) = \begin{cases} -U & |x| < a, \\ 0 & |x| > a. \end{cases}$$
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Examples of spherically symmetric potentials

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So, if this condition is not satisfied, the 3D spherical square well has no spherically symmetric stationary state: i.e. it has no ground state, and hence no bound states.

Remember: we stated (and will prove later) that the ground state of a particle in a spherically symmetric potential is always spherically symmetric As this illustrates, 3D potential wells (continuous potentials with $V(x) \le 0$ for all x, V(x) < 0 for some x, and V(x) = 0 for |x| > a, for some finite a) do not necessarily have bound states.

As this illustrates, 3D potential wells (continuous potentials with $V(x) \le 0$ for all x, V(x) < 0 for some x, and V(x) = 0 for |x| > a, for some finite a) do not necessarily have bound states. In contrast, we can show that all 1D potential wells have at least one bound state.

